



### Features

- Fast, easy-to-use TEACH-Mode programming; no potentiometer adjustments
- SPDT electromechanical relay for high-capacity switching
- Universal supply voltage: 48 to 250V ac / 24 to 250V dc
- Rugged encapsulated design for harsh environments
- Unique housing design allows for multiple mounting configurations
- Choose models with integral 2 m (6.5') or 9 m (30') cable, or with Mini-style or Micro-style quick-disconnect fitting
- Wide operating range of -20° to +70°C (-4° to +158°F)
- Temperature compensation



### Models

Models	Sensing Range	Cable*	Supply Voltage	Operation Mode	Output
QT50UVR3W	200 mm to 8 m (8" to 26')	5-wire, 2 m (6.5') cable	48 to 250V ac, 50/60 Hz / 24 to 250V dc	Window-limit (N.O. and N.C.)	SPDT electromechanical relay
QT50UVR3WQ1		5-pin Micro-style QD			
QT50UVR3WQ		5-pin Mini-style QD			
QT50UVR3F		5-wire, 2 m (6.5') cable		Fill-level control (pump-in and pump-out)	
QT50UVR3FQ1		5-pin Micro-style QD			
QT50UVR3FQ		5-pin Mini-style QD			

\* NOTES:

- 9 m cables are available by adding suffix "w/30" to the model number of a cabled sensor (e.g., QT50UVR3W w/30).
- A model with a QD connector requires a mating cable; see page 10.

Information about dc-voltage models is available on Banner's website: [www.bannerengineering.com](http://www.bannerengineering.com)



**WARNING . . . Not To Be Used for Personnel Protection**

**Never use these products as sensing devices for personnel protection. Doing so could lead to serious injury or death.**

These sensors do NOT include the self-checking redundant circuitry necessary to allow their use in personnel safety applications. A sensor failure or malfunction can cause either an energized or de-energized sensor output condition. Consult your current Banner Safety Products catalog for safety products which meet OSHA, ANSI and IEC standards for personnel protection.

# U-GAGE™ QT50U Series Sensor — Universal Voltage

## Principles of Operation

Ultrasonic sensors emit one or multiple pulses of ultrasonic energy, which travel through the air at the speed of sound. A portion of this energy reflects off the target and travels back to the sensor. The sensor measures the total time required for the energy to reach the target and return to the sensor. The distance to the object is then calculated using the following formula:

$$D = \frac{ct}{2}$$

**D** = distance from the sensor to the target  
**c** = speed of sound in air  
**t** = transit time for the ultrasonic pulse

To improve accuracy, an ultrasonic sensor may average the results of several pulses before outputting a new value.

## Temperature Effects

The speed of sound is dependent upon the composition, pressure and temperature of the gas in which it is traveling. For most ultrasonic applications, the composition and pressure of the gas are relatively fixed, while the temperature may fluctuate.

In air, the speed of sound varies with temperature according to the following approximation:

$$C_{m/s} = 20 \sqrt{273 + T_C}$$

**C<sub>m/s</sub>** = speed of sound in meters per second  
**T<sub>C</sub>** = temperature in °C

Or, in English units:

$$C_{ft/s} = 49 \sqrt{460 + T_F}$$

**C<sub>ft/s</sub>** = speed of sound in feet per second  
**T<sub>F</sub>** = temperature in °F

### Temperature Compensation

The speed of sound changes roughly 1% per 6° C (10° F). QT50U series ultrasonic sensors have temperature compensation available; temperature compensation will reduce the error due to temperature by about 90%.

Changes in air temperature affect the speed of sound, which in turn affects the distance reading measured by the sensor. An increase in air temperature shifts both sensing window limits farther away from the sensor. Conversely, a decrease in air temperature shifts both limits closer to the sensor. This shift is approximately 3.5% of the limit distance for a 20° C change in temperature. With temperature compensation enabled, the sensor will maintain the window limits to within 1.8% over the entire -20° to +70° C range.

### NOTES:

- If temperature compensation is enabled, exposure to direct sunlight can affect the sensor's ability to accurately compensate for changes in temperature.
- If the sensor is measuring across a temperature gradient, the compensation will be less effective.
- With temperature compensation enabled, the temperature warmup drift upon power-up is less than 1.0% of the sensing distance. After 30 minutes, the apparent switchpoint will be within 0.5% of the actual position. After 60 minutes, the apparent switchpoint will be within 0.3% of the actual position.

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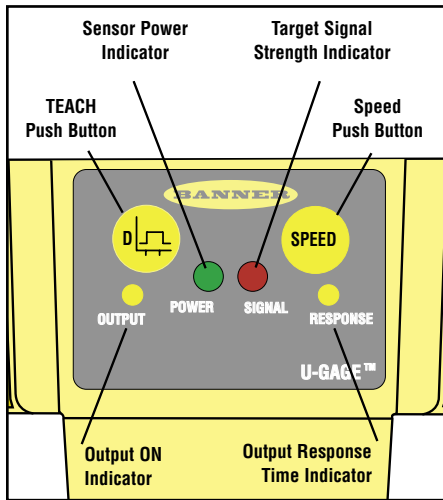


Figure 1. Sensor features





## Sensor Programming

Two TEACH methods may be used to program the sensor, using the TEACH push button:

- Teach individual minimum and maximum limits (see page 5), or
- Use the Auto-Window feature to center a sensing window around the taught position (see page 6).

## Sensor Configuration

The sensor can be configured for one of three output response times and to enable or disable temperature compensation. Both are accomplished using the sensor's Speed push button, using the procedures described below.

	Push Button Procedure $0.04 \leq \text{"click"} \leq 0.8 \text{ sec.}$		Result
Select Output Response Time	<b>RUN Mode</b>	<ul style="list-style-type: none"> <li>• No action required</li> </ul>	Response LED indicates the current Output Response Time setting: <ul style="list-style-type: none"> <li>• <b>ON Red</b> – Slow Response (1600 ms)</li> <li>• <b>ON Yellow</b> – Med. Response (400 ms)*</li> <li>• <b>OFF</b> – Fast Response (100 ms)</li> </ul>
	<b>Select Response Time</b>	<ul style="list-style-type: none"> <li>• “Click” the Speed push button until the desired Output Response Time is selected</li> </ul> 	<ul style="list-style-type: none"> <li>• Response LED cycles through <b>ON Red</b>, <b>ON Yellow</b>, and <b>OFF</b> to indicate selected Output Response Time (see above)</li> <li>• No further action required; sensor stores selection and remains in RUN mode</li> </ul>
Enable or Disable Temperature Compensation	<b>Enter Programming Mode</b>	<ul style="list-style-type: none"> <li>• Push and hold the Speed push button for 10 seconds</li> </ul> 	Response LED flashes: <ul style="list-style-type: none"> <li>• <b>Flashing Yellow</b> – Temperature Compensation is enabled*</li> <li>• <b>Flashing Red</b> – Temperature Compensation is disabled</li> </ul>
	<b>Enable/Disable</b>	<ul style="list-style-type: none"> <li>• “Click” the Speed push button to toggle between selections</li> </ul> 	Response LED flashes: <ul style="list-style-type: none"> <li>• <b>Flashing Yellow</b> – Temperature Compensation is enabled*</li> <li>• <b>Flashing Red</b> – Temperature Compensation is disabled</li> </ul>
	<b>Return to RUN Mode</b>	<ul style="list-style-type: none"> <li>• Push and hold the Speed push button for 10 seconds</li> </ul> 	<ul style="list-style-type: none"> <li>• Sensor stores selection</li> <li>• Sensor returns to RUN mode</li> <li>• Response LED returns to a solid color or OFF to indicate current Output Response Time setting</li> </ul>

\*Factory default settings

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## Status Indicators

**Power ON/OFF LED** (Green) – ON when sensor power is ON.

**Signal LED** (Red) – indicates incoming signal strength and condition.

Signal LED Status	Indicates
ON Bright	Good signal
ON Dim	Marginal signal strength
OFF	<ul style="list-style-type: none"><li>• No signal is received*, or</li><li>• Target is beyond the sensor's range limitations</li></ul>

\*If no signal is received, the output will react as if the target is beyond the far limit. The normally open output will be OFF, and the normally closed output will be ON.

**Output LED** (Yellow or Red) – indicates the target position relative to the window limits, or TEACH mode status.

Output LED Status	Indicates	
<b>RUN Mode</b>	<b>Window-Limit Sensor Models</b>	<b>Fill-Level Control Sensor Models</b>
ON Yellow	Target is within window limits	Level has dropped below far limit
OFF	Target is outside window limits	Level has risen above near limit
<b>TEACH Mode</b>		
ON Red	Waiting for first limit to be taught	
Flashing Red	Waiting for second limit to be taught	

**Response LED** (Yellow or Red) – indicates sensor output response time selection.

Response LED Status	Indicates
ON Red	Slow response (1600 ms)
ON Yellow	Medium response (400 ms)
OFF	Fast response (100 ms)

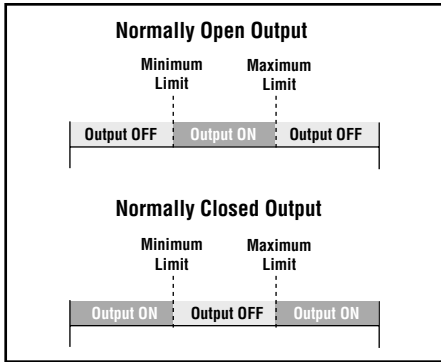





Figure 2. Teaching independent minimum and maximum limits – window limit models

## Teaching Minimum and Maximum Limits

Teach procedures are identical for window-limit and fill-level control models. Window-limit models function as shown in Figure 2, and fill-level control models function as shown in Figure 3. To readjust minimum or maximum limits, repeat the teach procedure.

	Push Button Procedure 0.04 ≤ “click” ≤ 0.8 sec.	Result
Programming Mode	<ul style="list-style-type: none"> <li>Push and hold TEACH push button for 2 seconds</li> </ul> 	<ul style="list-style-type: none"> <li>Output LED turns ON Red</li> <li>Sensor waits for first limit</li> </ul>
Teach First Limit	<ul style="list-style-type: none"> <li>Position the target for the first limit</li> <li>“Click” the TEACH push button</li> </ul> 	<ul style="list-style-type: none"> <li>Sensor learns the first limit position</li> <li>Output LED changes to Flashing Red</li> </ul>
Teach Second Limit	<ul style="list-style-type: none"> <li>Position the target for the second limit</li> <li>“Click” the TEACH push button</li> </ul> 	<ul style="list-style-type: none"> <li>Sensor stores both limits</li> <li>Output LED turns ON Yellow</li> <li>Sensor returns to RUN mode</li> </ul>

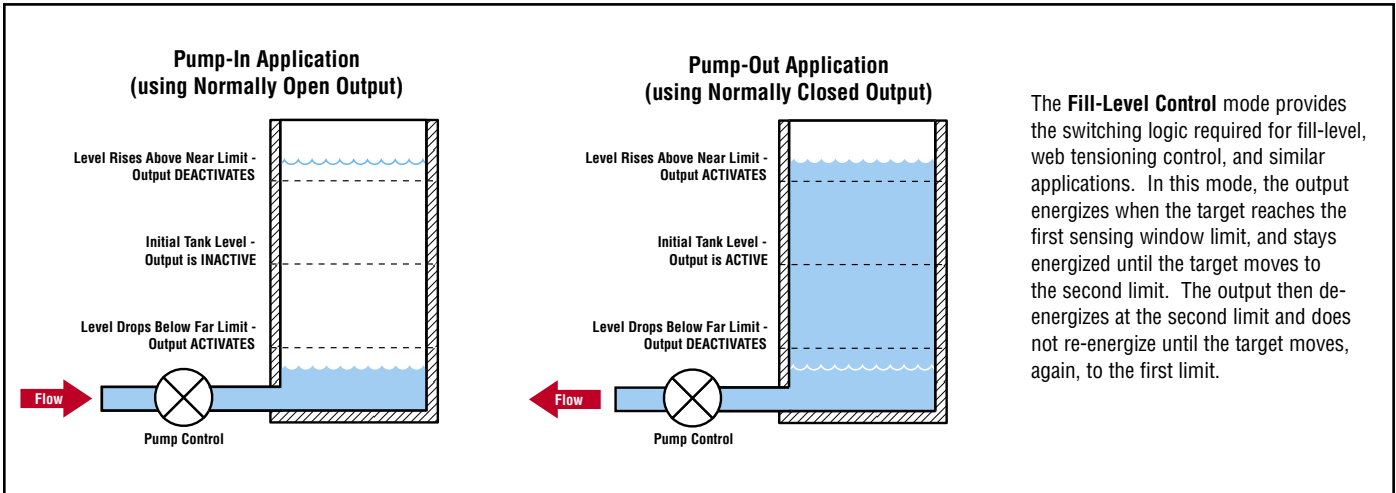





Figure 3. Fill-Level Control

The **Fill-Level Control** mode provides the switching logic required for fill-level, web tensioning control, and similar applications. In this mode, the output energizes when the target reaches the first sensing window limit, and stays energized until the target moves to the second limit. The output then de-energizes at the second limit and does not re-energize until the target moves, again, to the first limit.

# U-GAGE™ QT50U Series Sensor — Universal Voltage

## Teaching Limits Using the Auto-Window Feature

Teach procedures are identical for window-limit and fill-level control models. Teaching the same limit twice automatically centers a 200 mm window on the taught position. To readjust the sensing midpoint, repeat the teach procedure.

	Push Button Procedure 0.04 ≤ "click" ≤ 0.8 sec.	Result
<b>Programming Mode</b>	<ul style="list-style-type: none"> <li>Push and hold the TEACH push button for 2 seconds</li> </ul> 	<ul style="list-style-type: none"> <li>Output LED turns ON Red</li> <li>Sensor waits for the first limit</li> </ul>
<b>Teach Limit</b>	<ul style="list-style-type: none"> <li>Position the target at the desired midpoint for the sensing window</li> <li>"Click" the TEACH push button</li> </ul> 	<ul style="list-style-type: none"> <li>Output LED changes to flashing Red</li> </ul>
<b>Re-Teach Limit</b>	<ul style="list-style-type: none"> <li>Without moving the target, "click" the push button again</li> </ul> 	<ul style="list-style-type: none"> <li>Sensor stores sensing window</li> <li>Output LED turns ON Yellow</li> <li>Sensor returns to RUN mode</li> </ul>

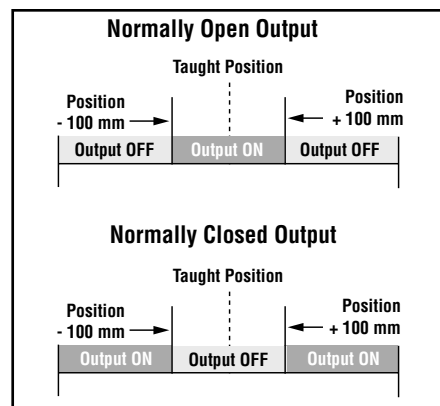


Figure 4. Using the Auto-Window feature for programming

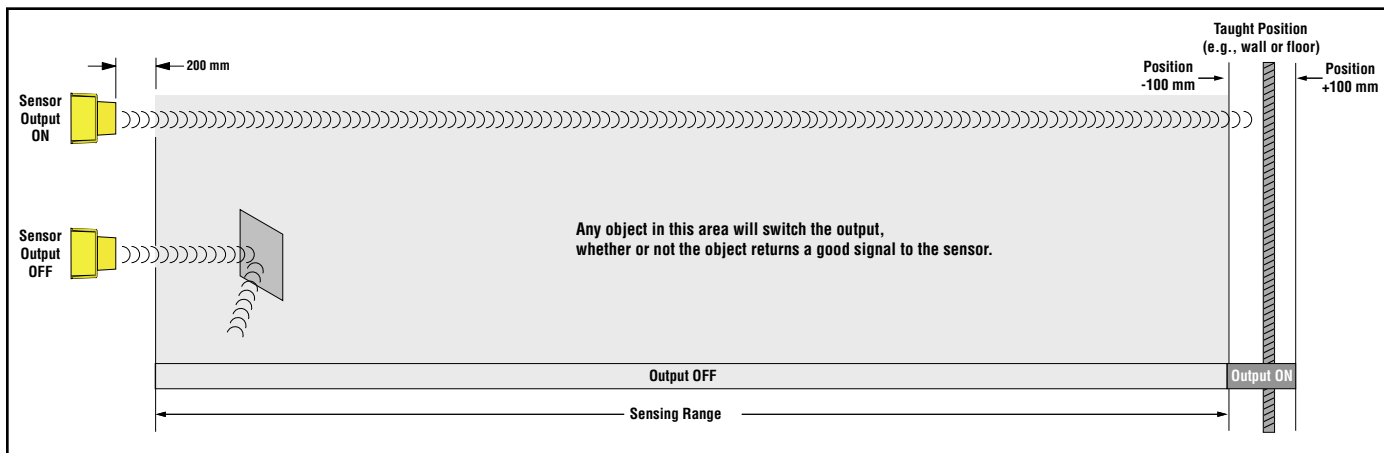



Figure 5. An application for Auto-Window feature (retroreflective mode)

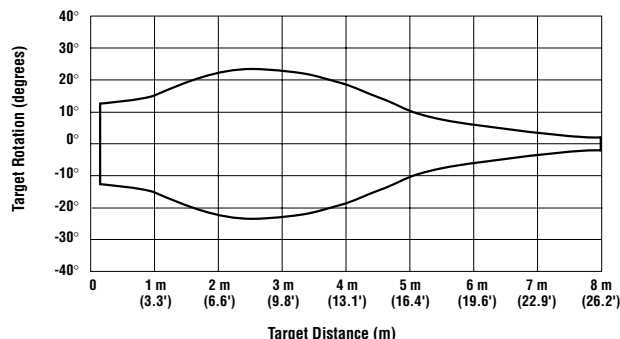
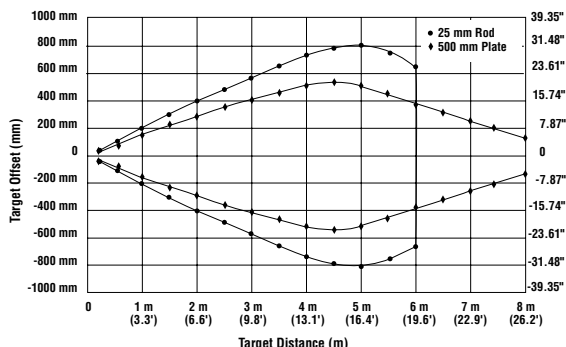
# U-GAGE™ QT50U Series Sensor — Universal Voltage

## Specifications

<b>Sensing Range</b>	200 mm to 8 m (8" to 26')
<b>Supply Voltage</b>	<b>Universal voltage:</b> 48 to 250V ac, 50/60 Hz / 24 to 250V dc (1.5 watts maximum, exclusive of load)
<b>Supply Protection Circuitry</b>	Protected against transient over voltages. DC hookup is without regard to polarity.
<b>Ultrasonic Frequency</b>	75 kHz burst, rep. rate 96 ms
<b>Delay at Power-up</b>	1.5 seconds
<b>Output Configuration</b>	SPDT (Single-Pole, Double-Throw) electromechanical relay output.
<b>Output Ratings</b>	<p><b>Max. switching power (resistive load):</b> 2000 VA, 240 W (1000VA, 120W for sensors with Micro-style QD)  <b>Max. switching voltage (resistive load):</b> 250V ac, 125V dc  <b>Max. switching current (resistive load):</b> 8A @ 250V ac, 8A @ 30V dc derated to 200 mA @ 125V dc (4A max. for sensors with Micro-style QD)</p> <p><b>Min. voltage and current:</b> 5V dc, 10 mA  <b>Mechanical life of relay:</b> 50,000,000 operations  <b>Electrical life of relay at full resistive load:</b> 100,000 operations</p> <p>NOTE: Transient suppression is recommended when switching inductive loads.</p>
<b>Output Response Time</b>	Selectable 1600 ms, 400 ms or 100 ms; see page 3.
<b>Temperature Effect</b>	<p><b>Uncompensated:</b> 0.2% of distance/°C  <b>Compensated:</b> 0.02% of distance/°C</p>
<b>Hysteresis</b>	<p><b>Window-Limit Sensor Models:</b> 5 mm  <b>Fill-Level Control Sensor Models:</b> 0 mm</p>
<b>Repeatability</b>	1.0 mm
<b>Minimum Window Size</b>	20 mm
<b>Adjustments</b>	<p><b>Sensing limits:</b> TEACH-Mode programming of near and far limits may be set using the TEACH push button (see pages 5 and 6).  <b>Sensor configuration:</b> Output response time and temperature compensation mode may be set using the Speed push button (see page 3).  <b>Factory default settings:</b> 400 ms output response time  Temperature compensation enabled</p>
<b>Indicators</b>	<p><b>Green Power On LED:</b> Indicates power is ON (see page 4).  <b>Red Signal LED:</b> Indicates target is within sensing range, and the condition of the received signal (see page 4).  <b>Output indicator (bicolor Yellow/Red):</b> Indicates output status or TEACH mode (see page 4).  <b>Response indicator (bicolor Yellow/Red):</b> Indicates output response time selection (see page 4).</p>
<b>Construction</b>	<p><b>Transducer:</b> Ceramic/Epoxy composite  <b>Housing:</b> ABS  <b>Membrane Switch:</b> Polyester</p>
<b>Operating Conditions</b>	<p><b>Temperature:</b> -20° to +70° C (-4° to +158° F)  <b>Maximum relative humidity:</b> 100%</p>
<b>Connections</b>	2 m (6.5') or 9 m (30') shielded 5-conductor (with drain) PVC jacketed attached cable or 5-pin Micro-style quick-disconnect or 5-pin Mini-style quick-disconnect
<b>Environmental Rating</b>	Leakproof design is rated IEC IP67; NEMA 6P
<b>Vibration and Mechanical Shock</b>	All models meet Mil Std. 202F requirements. Method 201A (vibration: 10 to 60Hz max., double amplitude 0.06", maximum acceleration 10G). Also meets IEC 947-5-2 requirements: 30G 11 ms duration, half sine wave
<b>Temperature Warmup Drift</b>	Less than 1.0% of sensing distance upon power-up with Temperature Compensation enabled (see Temperature Effects, page 2)
<b>Application Notes</b>	Objects passing inside the specified minimum sensing distance (200 mm) may produce a false response.
<b>Certifications</b>	

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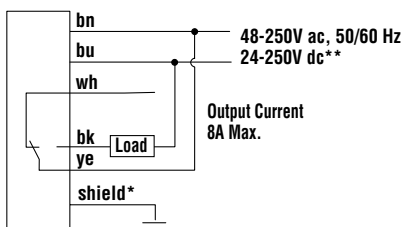
## Performance Curves



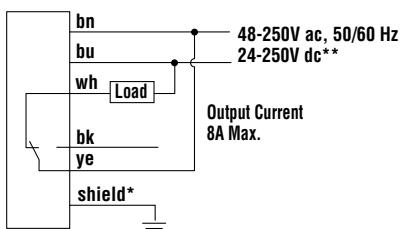
## Hookups

### Cabled Models

#### Normally Open/Pump-In

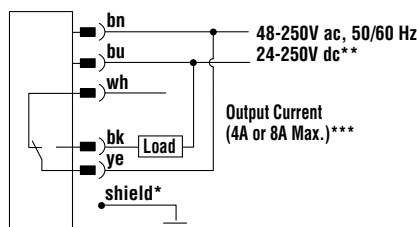


#### Normally Closed/Pump-Out

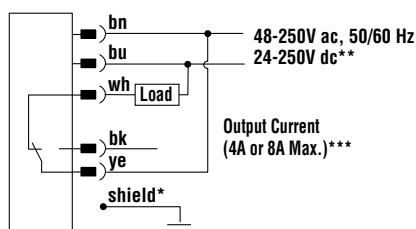


### QD Models

#### Normally Open/Pump-In



#### Normally Closed/Pump-Out



\*It is recommended that the shield wire be connected to earth ground.

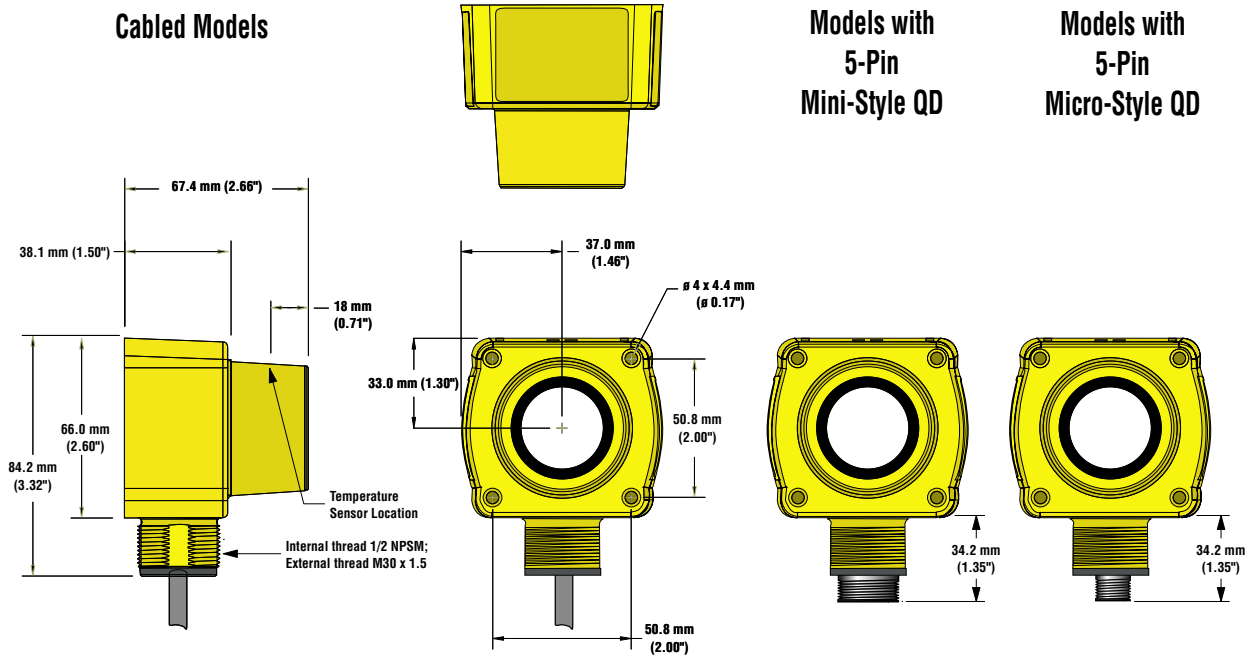
\*\*DC hookup is without regard to polarity.

\*\*\*4A max. for sensors with Micro-style QD; 8A max. for sensors with Mini-style QD.



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## Dimensions




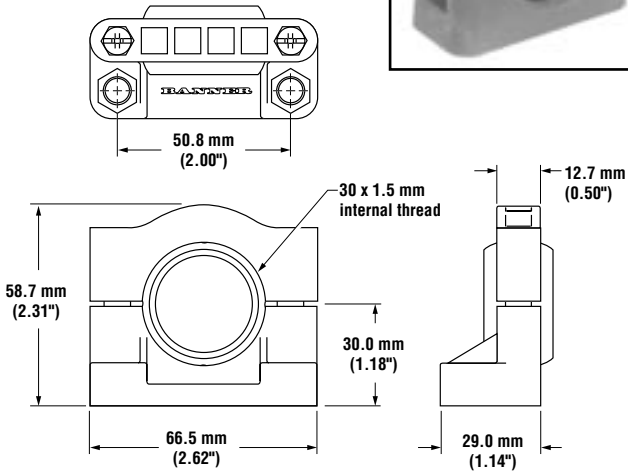

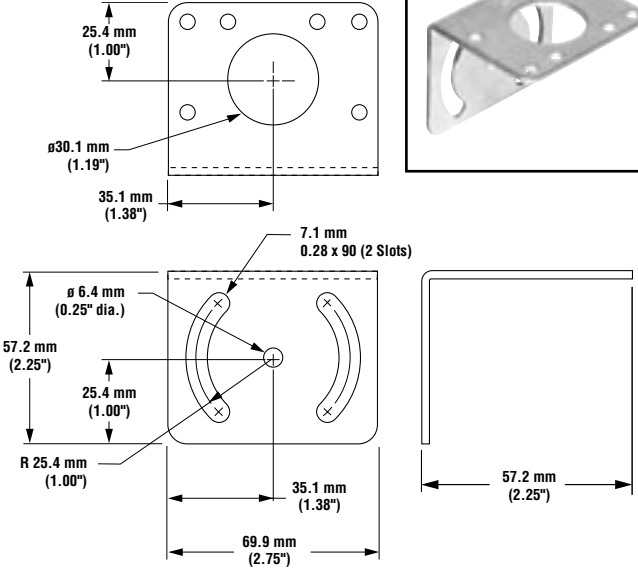
# U-GAGE™ QT50U Series Sensor — Universal Voltage

## Accessories

### Quick-Disconnect (QD) Cable

Style	Model	Length	Connector	Pin-Outs
5-Pin Mini-style with shield	<b>MBCC2-506</b> <b>MBCC2-512</b> <b>MBCC2-530</b>	2 m (6.5') 4 m (12') 9 m (30')		
5-Pin Micro-style Straight with shield	<b>MQVR3S-506</b> <b>MQVR3S-515</b> <b>MQVR3S-530</b>	2 m (6.5') 5 m (15') 9 m (30')		
5-Pin Micro-style Right-angle with shield	<b>MQVR3S-506RA</b> <b>MQVR3S-515RA</b> <b>MQVR3S-530RA</b>	2 m (6.5') 5 m (15') 9 m (30')		

### Mounting Brackets

<b>SMB30SC</b>	<ul style="list-style-type: none"> <li>• 30 mm split clamp with swivel, black reinforced thermoplastic polyester</li> <li>• Stainless steel hardware included</li> </ul>	<b>SMB30MM</b>	<ul style="list-style-type: none"> <li>• 30 mm, 11-gauge, stainless steel bracket with curved mounting slots for versatility and orientation</li> <li>• Clearance for M6 (1/4") hardware</li> </ul>
 		 	

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**WARRANTY:** Banner Engineering Corp. warrants its products to be free from defects for one year. Banner Engineering Corp. will repair or replace, free of charge, any product of its manufacture found to be defective at the time it is returned to the factory during the warranty period. This warranty does not cover damage or liability for the improper application of Banner products. This warranty is in lieu of any other warranty either expressed or implied.