Operating instructions
Safety light curtain

1. About this document

1.1 Function
This operating instructions manual provides all the information you need for the mounting, set-up and commissioning to ensure the safe operation and disassembly of the safety switchgear. The operating instructions must be available in a legible condition and a complete version in the vicinity of the device.

1.2 Target group: authorised qualified personnel
All operations described in this operating instructions manual must be carried out by trained specialist personnel, authorised by the plant operator only.

Please make sure that you have read and understood these operating instructions and that you know all applicable legislations regarding occupational safety and accident prevention prior to installation and putting the component into operation.

The machine builder must carefully select the harmonised standards to be complied with as well as other technical specifications for the selection, mounting and integration of the components.

1.3 Explanation of the symbols used

Information, hint, note:
This symbol is used for identifying useful additional information.

Caution: Failure to comply with this warning notice could lead to failures or malfunctions.
Warning: Failure to comply with this warning notice could lead to physical injury and/or damage to the machine.

1.4 Appropriate use
The products described in these operating instructions are developed to execute safety-related functions as part of an entire plant or machine. It is the responsibility of the manufacturer of a machine or plant to ensure the correct functionality of the entire machinery or plant.

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Translation of the original operating instructions

You will find the current version of the manual in your national language on the Internet, www.schmersal.net.

Vous trouverez le manuel de l'opérateur actuel de la moitié d'emploi dans votre langue nationale officielle sur l'Internet, www.schmersal.net.

U vindt de huidige versie van de gebruikershandleiding in uw officiële landstaal op het Internet, www.schmersal.net.

Encontrará el manual de instrucciones actual en su idioma oficial de la UE en nuestra página de Internet www.schmersal.net.

Il manuale d’istruzioni aggiornato nella vostra lingua (lingua ufficiale UE) è scaricabile in Internet all’indirizzo www.schmersal.net.
The safety switchgear must be exclusively used in accordance with the versions listed below or for the applications authorised by the manufacturer. Detailed information regarding the range of applications can be found in the chapter "Product description".

1.5 General safety instructions
The user must observe the safety instructions in this operating instructions manual, the country-specific installation standards as well as all prevailing safety regulations and accident prevention rules.

Further technical information can be found in the Schmersal catalogues or in the online catalogue on the Internet: www.schmersal.net.

The information contained in this operating instructions manual is provided without liability and is subject to technical modifications.

The entire concept of the control system, in which the safety component is integrated, must be validated to EN ISO 13849-2.

There are no residual risks, provided that the safety instructions as well as the instructions regarding mounting, commissioning, operation and maintenance are observed.

Additional measures could be required to ensure that the system does not present a dangerous breakdown, when other forms of light beams are available in a special application (e.g. use of wireless control devices on cranes, radiation of welding sparks or effects of stroboscopic lights).

1.6 Warning about misuse
In case of inadequate or improper use or manipulations of the safety switchgear, personal hazards or damages to machinery or plant components cannot be excluded. The relevant requirements of the standards EN ISO 13855 & EN ISO 13857 must be observed.

Only if the information described in this operating instructions manual are realised correctly, the safety function and therefore the compliance with the Machinery Directive is maintained.

1.7 Exclusion of liability
We shall accept no liability for damages and malfunctions resulting from defective mounting or failure to comply with this operating instructions manual. The manufacturer shall accept no liability for damages resulting from the use of unauthorised spare parts or accessories.

For safety reasons, invasive work on the device as well as arbitrary repairs, conversions and modifications to the device are strictly forbidden; the manufacturer shall accept no liability for damages resulting from such invasive work, arbitrary repairs, conversions and/or modifications to the device.

2. Product description
2.1 Destination and use
The SLC 440 is a non-contact, self-testing safety guard, which is used for the protection of hazardous points, hazardous areas and machine accesses. If one or more light beams are interrupted, the hazardous movement must be stopped.

The user must evaluate and design the safety chain in accordance with the relevant standards and the required safety level.

2.2 Ordering code
This operating instructions manual applies to the following types:

<table>
<thead>
<tr>
<th>No.</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>01</td>
<td>Protection field heights in mm available lengths:</td>
</tr>
<tr>
<td></td>
<td>0170, 0250, 0330, 0410, 0490, 0570, 0650, 0730,</td>
</tr>
<tr>
<td></td>
<td>0810, 0890, 0970, 1050, 1130, 1210, 1290, 1370,</td>
</tr>
<tr>
<td></td>
<td>1430, 1510, 1590, 1670, 1750, 1830</td>
</tr>
<tr>
<td>02</td>
<td>Resolution 14 mm with a range of 0.3 m ... 7 m</td>
</tr>
<tr>
<td>03</td>
<td>Resolution 30 mm with a range of 0.3 m ... 10 m</td>
</tr>
</tbody>
</table>

-01 = integrated status indication (option)
* only for resolution 30 mm

2.3 Special versions
For special versions, which are not listed in the order code, these specifications apply accordingly, provided that they correspond to the standard version.

2.4 Scope of delivery and accessories
2.4.1 Accessories included in delivery
Mounting kit MS-1100
The kit comprises 4 rotating mounting angles and 8 mounting screws for fixing to the end caps.

MSD5 spacer
The kit comprises 2 spacers and is included in delivery as of a protection field height of 1050 mm. Mounting recommended in case of vibrations.

2.4.2 Optional accessories
Centre support MS-1110
Consisting of 2 steel brackets and 4 spacers

Connecting cable for transmitter

<table>
<thead>
<tr>
<th>Item Number</th>
<th>Designation</th>
<th>Description</th>
<th>Length</th>
</tr>
</thead>
<tbody>
<tr>
<td>101207740</td>
<td>KA-0804</td>
<td>Female connector M12, 4-pole</td>
<td>5 m</td>
</tr>
<tr>
<td>101207741</td>
<td>KA-0805</td>
<td>Female connector M12, 4-pole</td>
<td>10 m</td>
</tr>
<tr>
<td>101207743</td>
<td>KA-0808</td>
<td>Female connector M12, 4-pole</td>
<td>20 m</td>
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</table>

Connecting cable for Receiver

<table>
<thead>
<tr>
<th>Item Number</th>
<th>Designation</th>
<th>Description</th>
<th>Length</th>
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<tr>
<td>101207728</td>
<td>KA-0904</td>
<td>Female connector M12, 8-pole</td>
<td>5 m</td>
</tr>
<tr>
<td>101207729</td>
<td>KA-0905</td>
<td>Female connector M12, 8-pole</td>
<td>10 m</td>
</tr>
<tr>
<td>101207730</td>
<td>KA-0908</td>
<td>Female connector M12, 8-pole</td>
<td>20 m</td>
</tr>
</tbody>
</table>

Adapter cable for parameter setting

<table>
<thead>
<tr>
<th>Item Number</th>
<th>Designation</th>
<th>Description</th>
<th>Length</th>
</tr>
</thead>
<tbody>
<tr>
<td>101217615</td>
<td>KA-0974</td>
<td>Y-distributor with command device</td>
<td>1 m</td>
</tr>
</tbody>
</table>

Test rod PLS
The test rod is used for testing the protection field.

MSD4 Vibration damper
Kit comprising: 8 vibration dampers 15 x 20 mm, 8x M5 socket head cap screws, 8 spring washers. Mounting using MS-1100).

The MSD4 vibration damper kit must be used for damping vibrations and oscillations on the safety light curtain SLC 440. For applications with higher mechanical stresses, e.g. presses, punching machines, we recommend the MSD4 kit. In this way, the availability of the safety light curtain SLC 440 is increased.

Integrated status indication
The SLC 440 series is also available with integrated status indication (red/green) installed onto the receiver.(See ordering code)
2.5 Technical data

Standards: EN 61496-1; CLC/TS 61496-2; EN ISO 13849; EN 62061

Material of the enclosure: Aluminium

Protection field heights:
- Resolution 14 mm: 170 mm - 1450 mm (170, 250, 330, 410, 490...)
- Resolution 30 mm: 170 mm - 1770 mm (170, 250, 330, 410, 490...)

Detection ability for test bodies: 14 mm and 30 mm

Range of the protection field:
- Resolution 14 mm: 0.3...7.0 m
- Resolution 30 mm: 0.3...10.0 m

Response time:
- beam coding (normal): 1 - 48 L = 10 ms, 49 - 144 L = 20 ms,
- without beam coding A: 1 - 48 L = 15 ms, 49 - 144 L = 27 ms

Rated operating voltage: 24 VDC ±10% (PELV) supply unit I_{max}, 2.0 A, to EN 60204

Rated operating current: 250 mA max. + 2 x 0.25 A each OSSD

Wavelength of the infrared radiation: 880 nm

Transmitter, infrared emitted radiation
- to DIN EN 12198-1: Category 0
- to DIN EN 62471: free group

Safety outputs

OSSD1, OSSD2: 2 x short-circuit proof PNP semi-conductor outputs

Test impulse cycle OSSD: 750 ms
Test impulse length: 100 µs
Switching voltage HIGH¹: 15 ... 26.4 V
Switching voltage LOW¹: 0 ... 2 V
Switching current each OSSD: 0 ... 250 mA
Leakage current²: 1 mA
Load capacity: 0 ... 2.2 µF
Load inductivity³: 0 ... 2 H

Admissible conduction resistance between OSSD and load: 2.5 Ω

Admissible conduction resistance of the supply cable: 1.5 Ω

Contactor control (EDM)

Input voltage HIGH (inactive): 11 ... 30 V
Input voltage LOW (active): 0 ... 2.0 V
Input current HIGH: 3 ... 10 mA
Input current LOW: 0 ... 2 mA

Input release restart interlock/restart interlock2

Input voltage HIGH (active): 11 ... 30 V
Input voltage LOW (inactive): 0 ... 2.0 V
Input current HIGH: 3 ... 10 mA
Input current LOW: 0 ... 3 mA

Functions:
- automatic mode, restart interlock, double reset, contactor control,
- beam blanking fixed and floating, beam coding A

Signal times

Contactor control: max. 500 ms
Restart interlock (manual reset): 50 ms ... 1.5 s, signal transmission in case of trailing edge
LED indications transmitter: Transmitting, status
LED indications receiver: OSSD ON, OSSD OFF, restart, signal reception, blanking, multifunction
Connection: M12 connector plug with metal thread, receiver 8-pole, transmitter 4-pole

Ambient temperature: -10°C ... +50°C
Storage temperature: -25°C ... +70°C

Interface:
- Diagnostics and function setting

Protection class:
- IP67 (IEC 60529)

Resistance to vibrations: 10 ... 55 Hz to IEC 60068-2-6
Resistance to shock: 10 g; 16 ms; to IEC 60068-2-29
Year of construction: as of 2012 version 1.1

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1) To IEC 61131-2
2) In case of failure, the leakage current at the most flows to the OSSD cable. The downstream control element must recognise this state as LOW. A safety PLC must detect this state.
3) The load inductivity generates an induced voltage during the switch-off, which compromises the downstream components (spark quenching element).

2.6 Response time (reaction time)
The response time depends on the height of the protected field, the resolution, the number of light beams and the beam coding A.

<table>
<thead>
<tr>
<th>Resolution 14 mm</th>
<th>Protection field height [mm]</th>
<th>Beams (Lines) [Number]</th>
<th>Response time [ms]</th>
<th>Response time with Beam coding A [ms]</th>
<th>Weight [kg]</th>
</tr>
</thead>
<tbody>
<tr>
<td>170</td>
<td>16</td>
<td>10</td>
<td>15</td>
<td>0.4</td>
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<tr>
<td>250</td>
<td>24</td>
<td>10</td>
<td>15</td>
<td>0.5</td>
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<tr>
<td>330</td>
<td>32</td>
<td>10</td>
<td>15</td>
<td>0.6</td>
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<tr>
<td>410</td>
<td>40</td>
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<tr>
<td>490</td>
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<td>570</td>
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<td>650</td>
<td>64</td>
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<td>27</td>
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<td></td>
</tr>
<tr>
<td>730</td>
<td>72</td>
<td>20</td>
<td>27</td>
<td>1.2</td>
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</tr>
<tr>
<td>810</td>
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<tr>
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<td>136</td>
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<td>27</td>
<td>2.2</td>
<td></td>
</tr>
<tr>
<td>1450</td>
<td>144</td>
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<td>27</td>
<td>2.3</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Resolution 30 mm</th>
<th>Protection field height [mm]</th>
<th>Beams (Lines) [Number]</th>
<th>Response time [ms]</th>
<th>Response time with Beam coding A [ms]</th>
<th>Weight [kg]</th>
</tr>
</thead>
<tbody>
<tr>
<td>170</td>
<td>8</td>
<td>10</td>
<td>15</td>
<td>0.4</td>
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<tr>
<td>250</td>
<td>12</td>
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<td>15</td>
<td>0.5</td>
<td></td>
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<td>330</td>
<td>16</td>
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<td>410</td>
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<td>490</td>
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<td>570</td>
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<tr>
<td>650</td>
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<td>730</td>
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<td>810</td>
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<td>970</td>
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<td>1.6</td>
<td></td>
</tr>
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<td>1050</td>
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<td>1.7</td>
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<tr>
<td>1130</td>
<td>56</td>
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<td>27</td>
<td>1.8</td>
<td></td>
</tr>
<tr>
<td>1210</td>
<td>60</td>
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<td>2.0</td>
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<td>1290</td>
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<td>1450</td>
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</tr>
<tr>
<td>1770</td>
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<td></td>
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</table>
2.7 Safety classification

<table>
<thead>
<tr>
<th>Standards</th>
<th>EN ISO 13849-1, EN 62061</th>
</tr>
</thead>
<tbody>
<tr>
<td>PL</td>
<td>up to e</td>
</tr>
<tr>
<td>Control category</td>
<td>up to 4</td>
</tr>
<tr>
<td>PFH value</td>
<td>$5.14 \times 10^9 / h$</td>
</tr>
<tr>
<td>SIL</td>
<td>up to 3</td>
</tr>
<tr>
<td>Service life</td>
<td>20 years</td>
</tr>
</tbody>
</table>

2.8 Functions

The system consists of a receiver and a transmitter. For the described functions, no further switching elements are required. The diagnostics and the function selection are performed by means of a command device (release button), see chapter "Parameter setting".

The system has the following features:
- Protective mode automatic (automatic start after release of the protection field)
- Restart interlock (manual reset)
- Double acknowledgement/reset
- Contactor control EDM
- Beam coding A
- Blankings of fixed protection field areas
- Blankings of fixed protection field areas with movable edge region
- Blankings of movable protection field areas

Factory setting

The system features many functions without needing any additional devices. The following table gives an overview of the possible functions and the factory settings configuration.

<table>
<thead>
<tr>
<th>Function</th>
<th>Factory setting</th>
<th>Configuration</th>
</tr>
</thead>
<tbody>
<tr>
<td>Protective mode, automatic</td>
<td>not active</td>
<td>External wiring</td>
</tr>
<tr>
<td>Restart interlock (manual reset)</td>
<td>not active</td>
<td>External wiring</td>
</tr>
<tr>
<td>Double acknowledgement/reset</td>
<td>not active</td>
<td>With command device</td>
</tr>
<tr>
<td>Blankings fixed/floating</td>
<td>not active</td>
<td>With command device</td>
</tr>
<tr>
<td>Contactor control (EDM)</td>
<td>not active</td>
<td>With command device</td>
</tr>
<tr>
<td>Beam coding A</td>
<td>not active</td>
<td>With command device</td>
</tr>
</tbody>
</table>

In supply condition, the restart interlock (manual reset) neither the protective mode is active. One of both operating modes must be wired in order to enable the OSSD outputs. If no operating mode is selected, the following message is shown:

**Status indication E1 + LED OSSD OFF (red)**

2.8.1 Protective mode / Automatic

The protective mode switches the OSSD outputs to the ON state (protection field not interrupted), without external release of a switching device.

**Wiring of the receiver:**

- Jumper connection pin 1 with pin 6

This operating mode generates an automatic restart of the machine if the protection field is not interrupted.

A 24 VDC H-signal at the input of pin 1 leads to a restart of the system. If the 24 VDC H-signal is still present at pin 1 after the self-test, the system switches to setting mode, see chapter "Setting mode".

2.8.2 Restart interlock (manual reset)

The restart interlock (manual reset) prevents an automatic enabling of the outputs (OSSD's ON state) after switch-on of the operating voltage or an interruption of the protection field. The system switches the outputs only to ON state, when an external command device (restart button) generates an enabling signal at the restart input (receiver).

**Wiring of the receiver:**

- Jumper connection pin 5 with pin 6
- Command device (enabling button) at pin 1

The command devices (enabling button) must be installed outside of the hazardous area. The operator must have a clear view on the hazardous area when actuating the enabling button.

2.8.3 Restart interlock with double acknowledgement/reset

In applications with access monitoring, a complete overview of the hazardous areas is often not possible; despite that, a reset of the command device for the restart interlock outside of the hazardous area by third parties is at all times enabled, although possible persons/operators are in the invisible area. This hazardous situation can be avoided by means of a double reset, i.e. integration of two command devices inside and outside the hazardous area.

**Wiring of the receiver:**

- Command device S1 at pin 1
- Command device S2 at pin 5
- Pin 6, no signal (input open)
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Specification:
The operating mode is available, when the parameter setting - double reset is activated (P 5). See chapter Parameter setting.

Sequence for enabling:
1) Actuate command device inside of the hazardous area (S2) and leave the hazardous area
2) Go through protected field or interrupt at least one beam, then release protected field
3) Actuate the command device outside of the hazardous area (S1)

Command device S1 can be reset (acknowledged) within a timeframe of 2 to 60 seconds after the actuation of S2. If the order or the time requirement is not respected, the process must be repeated.

Signalling: LED restart (yellow)

<table>
<thead>
<tr>
<th>Status</th>
<th>Note</th>
</tr>
</thead>
<tbody>
<tr>
<td>On</td>
<td>Release of S2 (restart interlock 2) waiting for signal</td>
</tr>
<tr>
<td>Flashing</td>
<td>Release of S1 (restart interlock) waiting for signal</td>
</tr>
</tbody>
</table>

2.8.4 Fixed blanking
The SLC 440 can blank stationary objects in the protection field.

Multiple protection field areas can be blanked. If small changes are made within the fixed blanking area, each time 1 beam can be additionally blanked to increase the tolerance. See chapter Parameter setting - Fixed blanking with movable edge regions (P 2).

The operating mode is only available, when the parameter setting - fixed blanking with movable edge region is activated (P 2). See chapter Parameter setting.
A combination with only fixed beam blanking (P 1) or additional floating beam blanking (P 3) is not possible.

2.8.5 Fixed blanking with movable edge region
This function can compensate slight position changes of a fixed blanked object with a change of +/- 1 beam. This position change corresponds to an amplitude of approx. +/- 10 mm / resolution 14 mm and approx. +/- 20 mm / resolution 30 mm upwards and downwards in the protection field.

Example of beam blanking (object in protection field)

<table>
<thead>
<tr>
<th>Beam number</th>
<th>Status OSSDs</th>
</tr>
</thead>
<tbody>
<tr>
<td>Fixed blanking, beam 4, 5 and 6</td>
<td>● ● ● ● ● Teach In</td>
</tr>
<tr>
<td>Shift 1 beam down</td>
<td>● ● ○ ○ ○ ok</td>
</tr>
<tr>
<td>Shift 1 beam up</td>
<td>○ ● ● ● ● ok</td>
</tr>
<tr>
<td>Object only covers 2 beams</td>
<td>○ ○ ● ● ● ok</td>
</tr>
<tr>
<td>Object only covers 2 beams</td>
<td>○ ○ ○ ○ ● ok</td>
</tr>
<tr>
<td>Object with downward edge displacement</td>
<td>● ● ● ● ● ok</td>
</tr>
<tr>
<td>Object with upward edge displacement</td>
<td>○ ○ ○ ○ ○ ok</td>
</tr>
<tr>
<td>Object displacement exceeds 1 beam</td>
<td>○ ○ ○ ● ● Error</td>
</tr>
<tr>
<td>Object size changed (1 beam)</td>
<td>○ ○ ● ● ● Error</td>
</tr>
<tr>
<td>Object size changed (5 beams)</td>
<td>● ● ● ● ● Error</td>
</tr>
</tbody>
</table>

The function is activated by means of the parameter setting (P1). If the function is activated, the LED blanking in the diagnostic window of the receiver starts flashing. See chapter Parameter settings.

The remaining lateral areas must be protected against intrusion by means of mechanical covers.
The lateral covers must be fixed with the object.
Partial covers are not authorised.
After the fixed blanking, the protection field must be tested by means of the test rod.
The restart interlock function of the safety light curtain or the machine must be activated.

The SLC 440 safety light curtain can blank movable objects in the protection field.

The SLC 440 can blank up to 2 beams (floating) in the protection field, see parameter setting (P 3). A combination of fixed and floating blanking (P 1 and P 3) is possible.
A combination of fixed blanking with movable edge region (P 2) and floating blanking (P 3) is not possible.
Safety light curtain

Operating instructions

Example:

Floating and fixed blanking

Legend:
1: Fixed blanking area
2: Floating blanking area

The function enables an arbitrary floating blanking of partial areas in the protection field. The first beam, which is located immediately behind the diagnostic window, cannot be blanked.

This function allows for an interruption of the protection height without the outputs being disabled in case of material movement in the protection field, e.g. material ejection or process-controlled material movement. This extension of the object detection increases the resolution. In this way, the physical resolution changes into an effective resolution. This effective resolution must be used to calculate the safety distance.

Use formula (1) of the chapter "Calculation of the safety distance" to calculate the safety distance with the effective resolution if a maximum of 2 light beams are blanked. The number of beams to be blanked is limited, see Table Effective resolution.

In a system with a 14 mm physical resolution, the effective resolution is increased to 34 mm in case of a floating blanking of 2 beams. The effective resolution must be registered permanently and clearly visible onto the label affixed to the receiver.

Effective resolution

The effective resolution in case of activated blanking of floating beams can be found in the following table:

<table>
<thead>
<tr>
<th>Resolution 14 mm</th>
<th>Blanked beams</th>
<th>Physical resolution</th>
<th>Effective resolution</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>14</td>
<td>24</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>14</td>
<td>34</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Resolution 30 mm</th>
<th>Blanked beams</th>
<th>Physical resolution</th>
<th>Effective resolution</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>30</td>
<td>48</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>30</td>
<td>68</td>
<td></td>
</tr>
</tbody>
</table>

The function is activated in parameter setting mode (P 3). If the function is activated, the LED blanking in the diagnostic window of the receiver starts flashing.

Perform a new calculation of the safety distance with the effective resolution. Adjust the safety distance in accordance with your calculation!

The standard IEC/TS 62046 includes information, which describes possibly required additional measures to prevent a person from reaching a hazard through the blanking areas of a protection field.

2.8.7 Contactor control (EDM)

The contactor control monitors the controlled switching elements (auxiliary contacts of the contactors) of both outputs. This monitoring is realised after each interruption of the protection field and prior to the restart (enabling) of the outputs. In this way, malfunctions of the contactors are detected, e.g. contact welding or contact spring breakage. If the light curtain detects a malfunction of the switching elements, the outputs are locked.

After elimination of the error, a power reset is required.

The contactor control is not activated upon delivery. The function is activated in parameter setting mode (P 4).

Connection EDM

Wiring of the receiver:
- Kn1, Kn2 = auxiliary contact of the last switching relay

The auxiliary contacts must only be connected, when the function is activated!

2.9 Self-test

The system performs a complete self-test and safety test within 2 seconds after the operating voltage has been switched on. If the protection field is not interrupted, the system switches to the ON condition (automatic mode). In case of an error, the outputs at the receiver do not switch to the ON state. An error message is emitted in the form of an error code. For more information, refer to chapter Fault diagnosis.

During operation, the system executes a cyclic self-test. Safety-relevant faults are detected within the reaction time and cause the outputs to be switched off and an error code to be emitted.

2.10 Beam coding A

The preset beam coding of the safety light curtain must be adjusted, when systems operating in each other's vicinity and a set-up as shown in the image below (no interference) is impossible. When supplied, the beam coding A is not active. A receiver with activated beam coding A can distinguish the beams of the transmitter with the same beam coding, which are destined to this particular receiver, from foreign beams.

If adjacent systems are operated without beam coding A, the user is at risk.

Perform a new calculation of the safety distance with the effective resolution. Adjust the safety distance in accordance with your calculation!

The auxiliary contacts must only be connected, when the function is activated!

The standard IEC/TS 62046 includes information, which describes possibly required additional measures to prevent a person from reaching a hazard through the blanking areas of a protection field.

2.8.7 Contactor control (EDM)

The contactor control monitors the controlled switching elements (auxiliary contacts of the contactors) of both outputs. This monitoring is realised after each interruption of the protection field and prior to the restart (enabling) of the outputs. In this way, malfunctions of the contactors are detected, e.g. contact welding or contact spring breakage. If the light curtain detects a malfunction of the switching elements, the outputs are locked.

After elimination of the error, a power reset is required.

The contactor control is not activated upon delivery. The function is activated in parameter setting mode (P 4).

Connection EDM

Wiring of the receiver:
- Kn1, Kn2 = auxiliary contact of the last switching relay

The auxiliary contacts must only be connected, when the function is activated!

2.9 Self-test

The system performs a complete self-test and safety test within 2 seconds after the operating voltage has been switched on. If the protection field is not interrupted, the system switches to the ON condition (automatic mode). In case of an error, the outputs at the receiver do not switch to the ON state. An error message is emitted in the form of an error code. For more information, refer to chapter Fault diagnosis.

During operation, the system executes a cyclic self-test. Safety-relevant faults are detected within the reaction time and cause the outputs to be switched off and an error code to be emitted.

2.10 Beam coding A

The preset beam coding of the safety light curtain must be adjusted, when systems operating in each other's vicinity and a set-up as shown in the image below (no interference) is impossible. When supplied, the beam coding A is not active. A receiver with activated beam coding A can distinguish the beams of the transmitter with the same beam coding, which are destined to this particular receiver, from foreign beams.

If adjacent systems are operated without beam coding A, the user is at risk.

Perform a new calculation of the safety distance with the effective resolution. Adjust the safety distance in accordance with your calculation!

The function is activated in parameter setting mode (P 3). If the function is activated, the LED blanking in the diagnostic window of the receiver starts flashing.

Perform a new calculation of the safety distance with the effective resolution. Adjust the safety distance in accordance with your calculation!

The standard IEC/TS 62046 includes information, which describes possibly required additional measures to prevent a person from reaching a hazard through the blanking areas of a protection field.

2.8.7 Contactor control (EDM)

The contactor control monitors the controlled switching elements (auxiliary contacts of the contactors) of both outputs. This monitoring is realised after each interruption of the protection field and prior to the restart (enabling) of the outputs. In this way, malfunctions of the contactors are detected, e.g. contact welding or contact spring breakage. If the light curtain detects a malfunction of the switching elements, the outputs are locked.

After elimination of the error, a power reset is required.

The contactor control is not activated upon delivery. The function is activated in parameter setting mode (P 4).

Connection EDM

Wiring of the receiver:
- Kn1, Kn2 = auxiliary contact of the last switching relay

The auxiliary contacts must only be connected, when the function is activated!

2.9 Self-test

The system performs a complete self-test and safety test within 2 seconds after the operating voltage has been switched on. If the protection field is not interrupted, the system switches to the ON condition (automatic mode). In case of an error, the outputs at the receiver do not switch to the ON state. An error message is emitted in the form of an error code. For more information, refer to chapter Fault diagnosis.

During operation, the system executes a cyclic self-test. Safety-relevant faults are detected within the reaction time and cause the outputs to be switched off and an error code to be emitted.

2.10 Beam coding A

The preset beam coding of the safety light curtain must be adjusted, when systems operating in each other's vicinity and a set-up as shown in the image below (no interference) is impossible. When supplied, the beam coding A is not active. A receiver with activated beam coding A can distinguish the beams of the transmitter with the same beam coding, which are destined to this particular receiver, from foreign beams.

If adjacent systems are operated without beam coding A, the user is at risk.

Perform a new calculation of the safety distance with the effective resolution. Adjust the safety distance in accordance with your calculation!

The function is activated in parameter setting mode (P 3). If the function is activated, the LED blanking in the diagnostic window of the receiver starts flashing.

Perform a new calculation of the safety distance with the effective resolution. Adjust the safety distance in accordance with your calculation!

The standard IEC/TS 62046 includes information, which describes possibly required additional measures to prevent a person from reaching a hazard through the blanking areas of a protection field.
Operating instructions
Safety light curtain

SLC 440

Transmitter parameter setting:

Transmitter connection:
- Jumper connection pin 1 with pin 2
- Jumper connection pin 3 with pin 4

The response time of the system is increased when beam coding A is used. To this end, the safety distance must be adjusted. Refer to chapter Response time.

2.11 Parameter setting
The parameter setting of the SLC 440 enables the individual adjustment of the desired functionality to the application.

Parameter display (7-segment display):
- A = parameter active
- - = parameter not active
- S. = save the current configuration
- C. = delete the current configuration, new configuration = factory setting
- n = unavailable (unauthorised setting, refer to Parameter setting information)
- d. = diagnostic/setting mode

Parameter selection:
Selection, change and acceptance of the parameters by means of the command device pushbutton S1:
- Switch to parameter setting Px: briefly press the button 0.1 ... 1.5 sec.
- Change parameter setting Px: press button 2.5 ... 6 sec.
- Save S. /Factory setting C.: press button 2.5 ... 6 sec.

Procedure:
1) For the parameter setting, the receiver must be isolated from the operating voltage. In de-energised condition, the following jumper connection and the pushbutton S1 must be connected.

2) The receiver switches to parameter setting mode when the operating voltage is switched on.

Wiring of the receiver:
- Jumper connection from DOUT (Pin 6) to EDM (Pin 8)
- Connection of the command device pushbutton S1 (+24 VDC) on Pin 1 (restart interlock)
- Possible jumper connections from Pin 5 to Pin 6 or Pin 1 to Pin 6 must be removed. If the EDM function was activated, the auxiliary contact of Pin 8 must be removed.

The operating status is signalled in the following way:

- 7-segment display
- LED OSSD ON (red) active
- LED OSSD OFF (green) active

Parameter setting:
1) When S1 is briefly pressed, the display shows repeatedly
- (Parameter P 1 not active, factory setting)

2) Select the desired parameter by means of command device S1 (briefly press the button).
3) Select the desired parameter by means of the command device (press the button for a long time):
   1. Push button (approx. 2.5 seconds) ➔ - flashes (parameter not active)
   2. Enable button when ➔ A static (parameter active)
4) Save the new configuration with the parameter Save S. (push the button for a long time):
   1. Actuate button (approx. 2.5 seconds) ➔ S. flashes
   2. Enable button when ➔ S. static
   3. Automatic restart ➔ "segment circulation" then P is displayed (saving operation successful)

If no restart takes place (S.), the saving operation has not been successful (i.e. the parameter changes have not been saved). The procedure 1 to 3 must be repeated.

All parameters can be reset to the factory setting using the parameter C. (clear/delete):
1) Actuate the button (approx. 2.5 seconds) ➔ C. flashes
2) Enable the button when ➔ C. static
3) Automatic restart ➔ "Segment circulation", then P is displayed (all parameters have been deleted)

Return to normal operating mode:
1. Switch off the operating voltage at the receiver
2. Remove jumper connection at the receiver DOUT (Pin 6) and EDM (Pin 8)
3. Select the desired operating mode (jumper connections)
4. Switch operating voltage on

Adapter cable for parameter setting
If the wiring for the parameter setting of the receiver is not accessible, the KA-0974 adapter cable can be used as an alternative. The adapter cable is connected between the connecting cable and the cable connector of the receiver. The parameters are set by means of the command device (pushbutton), as described in the parameter setting. After the parameters have been set, the KA-0974 is removed and the connecting cable is connected to the receiver.

Legend:
1 = Connecting cable Receiver
2 = Command device pushbutton for release
Table Parameter setting

<table>
<thead>
<tr>
<th>No.</th>
<th>Parameter</th>
<th>Status</th>
<th>Note</th>
</tr>
</thead>
<tbody>
<tr>
<td>P 1</td>
<td>Fixed blanking</td>
<td>– = not active</td>
<td>Position active saves all interrupted beam through</td>
</tr>
<tr>
<td></td>
<td></td>
<td>A = Active</td>
<td>Teach-in mode</td>
</tr>
<tr>
<td>P 2</td>
<td>Fixed blanking with movable edge region</td>
<td>– = not active</td>
<td>Tolerance in edge region +/− 1 beam - adjust safety distance!</td>
</tr>
<tr>
<td></td>
<td></td>
<td>A = Active</td>
<td></td>
</tr>
<tr>
<td>P 3</td>
<td>Floating blanking 1 beam or 2 beams</td>
<td>– = not active</td>
<td>Blanking of max.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 = 1 beam</td>
<td>2 beams - adjust safety distance!</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 = 2 beams</td>
<td></td>
</tr>
<tr>
<td>P 4</td>
<td>Contactor control/EDM</td>
<td>– = not active</td>
<td>The auxiliary (NC) contacts are monitored</td>
</tr>
<tr>
<td></td>
<td></td>
<td>A = Active</td>
<td></td>
</tr>
<tr>
<td>P 5</td>
<td>Double acknowledgement with command device restart interlock N° 2</td>
<td>– = not active</td>
<td>Operating mode &quot;Protective mode with double reset* restart n° 2&quot;</td>
</tr>
<tr>
<td></td>
<td></td>
<td>A = Active</td>
<td></td>
</tr>
<tr>
<td>P 6</td>
<td>Beam coding A (alternative)</td>
<td>– = not active</td>
<td>Activating upon mutual interference of identical systems</td>
</tr>
<tr>
<td></td>
<td></td>
<td>A = Active</td>
<td></td>
</tr>
<tr>
<td>S</td>
<td>Save</td>
<td>S</td>
<td>Press button S1 to save changes (2.5...6 sec.)</td>
</tr>
<tr>
<td>C</td>
<td>Clear/delete</td>
<td>C</td>
<td>Press button S1 to save factory setting (2.5...6 sec.)</td>
</tr>
<tr>
<td>d.</td>
<td>Diagnostic/setting mode</td>
<td>d</td>
<td>Switch to setting mode</td>
</tr>
</tbody>
</table>

3. Mounting

3.1 General conditions

The following guidelines are provided as preventive warning notices to ensure a safe and appropriate handling. These guidelines are an essential part of the safety instructions and therefore must always be observed and respected.

- The SLC must not be used on machines, which can be stopped electrically in case of emergency.
- The safety distance between the SLC and a hazardous machine movement must always be observed and respected.
- Additional mechanical safety guards must be installed so that the operator has to pass by the protection field to reach the hazardous machine parts.
- The SLC must be installed so that the personnel always must be within the detection zone when operating the machine. An incorrect installation can lead to serious injuries.
- Never connect the outputs to +24VDC. If the outputs are wired to +24VDC, they are in ON state, as a result of which they are unable to stop a hazardous situation occurring on the application/machine.
- The safety inspections must be conducted regularly.
- The SLC must not be exposed to inflammable or explosive gasses.
- The connecting cables must be connected in accordance with the installation instructions.
- The fixing screws of the end caps and the mounting angle must be firmly tightened.

3.2 Protection field and approach

The protection field of the SLC consists of the entire range located between the protection field markings of transmitter and receiver. Additional protective devices must ensure that the operator has to pass by the protection field to reach the hazardous machine parts.

P 1 or P 2 - - When fixed blanking is activated, all beams that are interrupted in the protection field at the time that command device S1 is actuated (> 2.5 sec. with trailing edge) are blanked.
P 2 - - Parameter combination P 1 and P 2 or P 2 and P 3 is not authorised. Status indication n = not available.
P 6 - - Beam coding A must also be set at the transmitter, refer to chapter Beam coding A

Correct installation

Hazardous machine parts can only be reached after passing through the protection field.

The presence of staff members between the protection field and hazardous machine parts must be prevented/avoided (protection against stepping over).

Unauthorised installation

Hazardous machine parts can be reached without passing through the protection field.

The presence of staff members between the protection field and hazardous machine parts is enabled.
3.3 Alignment of the sensors

Procedure:
1. The transmitter and the receiver must be fitted parallel to each other and at the same height.
2. Choose the operating mode "Automatic" (see chapter Protective mode/automatic) and switch the operating voltage on.
3. The 7-segment display in the receiver shows the current signal quality/ fine setting (signalling, see chapter "setting mode") for 30 seconds. First turn the transmitter, then the receiver towards each other until the best possible signal quality of 3 crossbars is obtained (7-segment display) (note: 2 crossbars = sufficient). Fix this position with both screws for each mounting angle.

If the setting is not possible within 30 seconds, change to setting mode (see chapter "setting mode"). The setting mode leads to the best possible positioning of the sensors through the basic setting (position of the second and last beam) and the optimisation of with the fine setting (total signal).

**Status indication of the LED’s:** OSSD ON (green) is active (ON), signal quality (orange) not active

4. After the positioning, the suitable operating mode (restart interlock) must be chosen for the application.

3.4 Setting mode

**Setting tool with 7-segment display**
The function supports the best possible alignment between transmitter and receiver. The signal represents the signal strength at the individual receivers, whilst the outputs OSSD 1, 2 remain disabled. For the optical representation of the signal quality, two ranges, the signal strength at the 2nd and the last beam in the protection field (basic setting) and the optimal alignment quality of all beams (fine adjustment) are available.

**Activating setting mode:**
After the system start, a signal impulse (H signal 24 VDC) must be present at the input restart interlock (pin 1) of the receiver for at least 2.0 seconds (pushbutton/enabling).
The 7-segment display takes place with the basic setting display (vertical bars). The system must be aligned parallel and at-grade compared to each other and be fixed with the mounting angle in such manner that both segments reach a signal strength of 50% to 100%.

By means of another signal impulse at input restart (Pin 1), it is possible to switch between basic and fine adjustment, as long as the height of the signal strength indicates 50% of the basic setting (vertical bar). After the setting of the sensors, the setting mode can be terminated by the presence of a H-signal at pin 1 for at least 2.5 seconds (max. 6 seconds) and the actuation of the enabling button or by a voltage reset at the receiver (+UB).

**Beam (a) = receive signal OK**
**Beam (b) = no receive signal**
**Beam (a) and beam (b) = receive signals OK**

**Basic setting indication:**
The signal strength is displayed per beam with two segments for the 2nd (a) and the last (b) beam.

- **Status second beam (a)**
- **Status last beam (b)**
- 2 segments left-hand side = signal strength of the **second** beam (a)
- 2 segments right-hand side = signal strength of the **last** beam (b)
- Signal strength (a) 25% ... 50%
- Signal strength (b) 0%
- Signal strength (a) 50% ... 100%
- Signal strength (b) 0%
- Signal strength (a) 50% ... 100%
- Signal strength (b) 25% ... 50%
- Signal strength (a) 50% ... 100%
- Signal strength (b) 50% ... 100%
- Inadequate alignment of the sensors (height offset, not parallel)
### Indication fine adjustment:
The fine adjustment is displayed by means of up to 3 segments (crossbars) for the best possible signal strength of all beams.

- **Best possible signal strength**
- **Signal strength for normal operation OK**
- **Signal strength OK, if one or more beams in the protection field are covered (beam blanking)**
- **Signal strength insufficient, when no beams are covered**

The safe operating status (high availability) is also ensured, when the best possible signal strength (3 crossbars) is not obtained due to soiling of the profiles or installation at nominal range.

### 3.5 Safety distance

The safety distance is the minimum distance between the protection field of the safety light curtain and the hazardous area. The safety distance must be observed to ensure that the hazardous area cannot be reached before the hazardous movement has come to standstill.

#### Calculation of the safety distance to EN ISO 13855 and EN ISO 13857

The safety distance depends on the following elements:
- Stopping time of the machine (calculation by run-on time measurement)
- Response time of the machine and the safety light curtain and the downstream relay (entire safety guard)
- Approach speed
- Resolution of the safety light curtain

#### Safety light curtain SLC 440

The safety distance for resolutions 14 mm up to 40 mm is calculated by means of the following formula:

\[
(1) \quad S = 2000 \text{ mm/s} \times T + 8(\ d - 14) \ [\text{mm}]
\]

- **S** = Safety distance [mm]
- **T** = Total reaction time (machine stopping time, reaction time of the safety guard, relays, etc.)
- **d** = Resolution of the safety light curtain

The approach speed is covered with a value of 2000 mm/s

If value \( S \leq 500 \text{ mm} \) after the calculation of the safety distance, then use this value.

If value \( S > 500 \text{ mm} \), recalculate the distance:

\[
(2) \quad S = 1600 \text{ mm/s} \times T + 8(\ d - 14) \ [\text{mm}]
\]

If the new value \( S > 500 \text{ mm} \), use this value as safety distance.

If the new value \( S < 500 \text{ mm} \), use a minimum distance of 500 mm.

**Example:**

- Reaction time of the safety light curtain = 10 ms
- Resolution of the safety light curtain = 14 mm
- Stopping time of the machine = 330 ms

\[
S = 2000 \text{ mm/s} \times (330 \text{ ms} + 10 \text{ ms}) + 8(14 \text{ mm} - 14 \text{ mm})
\]

\[
S = 680 \text{ mm}
\]

\[
S = > 500 \text{ mm}, \text{ therefore new calculation with } V = 1600 \text{ mm/s}
\]

\[
S = 544 \text{ mm}
\]

The safety distance for resolution > 40 mm is calculated by means of the following formula:

\[
(3) \quad S = (1600 \text{ mm/s} \times T) + 850 \text{ mm}
\]

- **S** = Safety distance [mm]
- **T** = Stopping time of the machine + reaction time of the safety light curtain
- **K** = Approach speed 1600 mm/s
- **C** = Safety supplement 850 mm

The safety distance between the safety light curtain and the hazardous point must always be respected and observed. If a person reaches the hazardous point before the hazardous movement has come to standstill, he/she is exposed to serious injuries.

### Safety distance to the hazardous area

Distance between the safety light curtain and the hazardous area is illustrated by the diagram. The distance must be calculated according to EN ISO 13855 and EN ISO 13857. If an overlap of the protection field is possible, take care to calculate the safety distance referring to additional CRO according to the table A1 as per norm EN ISO 13855.
3.5.1 Minimum distance to reflecting surfaces

During the installation, the effects of reflecting surfaces must be taken into account. In case of an incorrect installation, interruptions of the protection field could possibly not be detected, which could lead to serious injuries. The hereafter-specified minimum distances with regard to reflecting surfaces (metal walls, floors, ceilings or parts) must be imperatively observed.

Calculate the minimum distance to reflecting surfaces as a function of the distance with an aperture angles of ± 2.5° degrees or use the value from the table below:

<table>
<thead>
<tr>
<th>Distance between transmitter and receiver [m]</th>
<th>Minimum distance a [mm]</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.2 ... 3.0</td>
<td>130</td>
</tr>
<tr>
<td>4</td>
<td>175</td>
</tr>
<tr>
<td>5</td>
<td>220</td>
</tr>
<tr>
<td>7</td>
<td>310</td>
</tr>
<tr>
<td>10</td>
<td>440</td>
</tr>
</tbody>
</table>

Formula: \( a = \tan 2.5° \times L \) [mm]

- \( a \) = Minimum distance to reflecting surfaces
- \( L \) = Distance between transmitter and receiver

3.6 Dimensions transmitter and receiver

All measurements in mm.
Operating instructions
Safety light curtain

The overall length Ls (dimension end cap with regard to the cable connection up to the connector M12) of the sensors is calculated in the following way:

\[ Ls = \text{size } B - 13 \text{ mm} \]

**Example SLC440-ER-0970:**
\[ Ls = 1064 - 13 \text{ mm} \]
\[ Ls = 1051 \text{ mm} \]

**3.7 Fixing**

**Included in delivery:**

**Mounting kit MS-1100**
The mounting kit consists of 4 steel angles and 8 fixing screws.

**Optional accessories**

**Centre support MS-1110**
Mounting kit consisting of 2 steel angles and 4 spacers for central fixing

**Integrated status indication**
The status indication at the receiver indicates the switching condition of the outputs OSSD1 and OSSD2.

Green = outputs H-signal 24V
Red = outputs L-signal 0V

The integrated status indication **does not** change the mounting dimension B or the overall length C. The overall length of the Ls receiver increased by 10 mm.

**MSD5 spacer**
The kit consists of 2 spacers. Available as of protection field height of 1050 mm. Mounting recommended in case of vibrations.
4. Electrical connection

4.1 Wiring example

**Restart interlock (manual reset) (bridge 1)**
By bridging restart 2 (pin 5) and DOUT (pin 6), the restart interlock (manual reset) is activated. Connect S1 to Pin1.

**Protective mode / Automatic active (bridge 2)**
By bridging DOUT (Pin 6) and enable restart (Pin1), the protective mode is activated. **Do not connect S1.**

K1, K2: relay for processing the switching outputs OSSD 1, OSSD 2
Kn1, Kn2: auxiliary contacts of the last switching relay (optional) signals at input EDM (Pin 8)
Only to be connected when the contactor control is activated.

S1: command device pushbutton for restart (optional)
E1: power supply 24 VDC ± 10%
Operating instructions
Safety light curtain

4.2 Wiring example SLC 440

Connect COD 1 / COD 2 only when beam coding A is activated!

The colour codes are only valid for the cable types mentioned below "optional accessories".

For UL evaluated products we do recommend to use the UL style cable 20549.

5. Set-up and maintenance

5.1 Check before start-up
Prior to start-up, the following items must be checked by the responsible person.

Wiring check prior to start-up
1. The voltage supply is a 24V direct current power supply, (refer to technical data), which meets the CE Directives, Low Voltage Directives. A power downtime of 20 ms must be bridged.
2. Presence of a voltage supply with correct polarity at the SLC.
3. The connecting cable of the transmitter is correctly connected to the transmitter and the connecting cable of the receiver correctly to the receiver.
4. The double insulation between the light curtain output and an external potential is guaranteed.
5. The outputs OSSD1 and OSSD2 are not connected to +24 VDC.
6. The connected switching elements (load) are not connected to +24 VDC.
7. If two or more SLC are used within close range compared to each other, an alternating arrangement must be observed. Any mutual interference of the systems must be prevented (see chapter "Beam coding").

Switch the SLC on and check the operation in the following way:
The component performs a system test during approx. 2 seconds after the operating voltage has been switched on (indication through 7-segment display). After that, the outputs are enabled, if the protection field is not interrupted. The LED "OSSD ON" at the receiver is on.

In case of incorrect functionality, please follow the instructions listed in the chapter Fault diagnostic.

5.2 Maintenance
Do not use the SLC before the next inspection is terminated. An incorrect inspection can lead to serious and mortal injuries.

Conditions
For safety reasons, all inspection results must be archived. The operating principle of the SLC and the machine must be known in order to be able to conduct an inspection. If the fitter, the planning technician and the operator are different persons, please make sure that the user has the necessary information at his disposal to be able conduct the maintenance.
5.3 Regular check
A regular visual inspection and functional test, including the following steps, is recommended:
1. The component does not have any visible damages.
2. The optics cover is not scratched or soiled.
3. Hazardous machinery parts can only be accessed by passing through the protection field of the SLC.
4. The staff remains within the detection area, when works are conducted on hazardous machinery parts.
5. The safety distance of the application exceeds the mathematically calculated one.

Operate the machine and check whether the hazardous movement stops under the hereafter-mentioned circumstances.
1. Hazardous machine parts do not move when the protection field is interrupted.
2. The hazardous machine movement is immediately stopped, when the protection field is interrupted with the test rod immediately before the transmitter, immediately before the receiver and in the middle between the transmitter and the receiver.
3. No hazardous machine movement when the test rod is within the protection field.
4. The hazardous machine movement comes to standstill, when the voltage supply of the SLC is switched off.

5.4 Half-yearly inspection
The following items must be checked every six months or when a machine setting is changed.
1. Machine stops or does not inhibit any safety function.
2. No machine modification or connection change, which affects the safety system, has taken place.
3. The outputs of the SLC are correctly connected to the machine.
4. The total response time of the machine does not exceed the response time calculated during the first putting into operation.
5. The cables, the connectors, the caps and the mounting angles are in perfect condition.

5.5 Cleaning
If the optics cover of the sensors is extremely soiled, the OSSD outputs can be disabled. Clean with a clean, soft cloth with exercising pressure. The use of aggressive, abrasive or scratching cleaning agents, which could attack the surface, is prohibited.

6. Diagnostic

6.1 Status information LED

<table>
<thead>
<tr>
<th>Receiver</th>
<th>Function</th>
<th>LED colour</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Protection field</td>
<td>OSSD ON</td>
<td>green</td>
<td>Safety outputs Signal condition ON</td>
</tr>
<tr>
<td>OSSD OFF</td>
<td>red</td>
<td>Safety outputs Signal condition OFF</td>
<td></td>
</tr>
<tr>
<td>Restart</td>
<td>yellow</td>
<td>Input for command device</td>
<td></td>
</tr>
<tr>
<td>Signal reception</td>
<td>Blankling Information</td>
<td>orange</td>
<td>Safety-monitoring module of Signal reception</td>
</tr>
<tr>
<td></td>
<td>blue</td>
<td>Protection field(s) inactive (blanking)</td>
<td></td>
</tr>
<tr>
<td>Information</td>
<td>yellow-green</td>
<td>Beam coding A</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Transmitter</th>
<th>Function</th>
<th>LED colour</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Protection field</td>
<td>Information</td>
<td>green</td>
<td>Function display, Beam coding A</td>
</tr>
<tr>
<td>Transmitter</td>
<td>Transmitting</td>
<td>orange</td>
<td>Transmitter active</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Receiver LED</th>
<th>Status LED</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>OSSD ON</td>
<td>On</td>
<td>Protection field clear</td>
</tr>
<tr>
<td>OSSD OFF</td>
<td>On</td>
<td>Protection field interrupted, system or configuration error</td>
</tr>
<tr>
<td>On</td>
<td>Error output refer to Fault diagnostic table</td>
<td></td>
</tr>
<tr>
<td>Restart</td>
<td>On</td>
<td>Restart interlock (manual reset) active, signal expected at input restart interlock</td>
</tr>
<tr>
<td>Signal reception</td>
<td>On/flashing</td>
<td>Signal reception too low; check alignment and installation height between transmitter and receiver</td>
</tr>
<tr>
<td>Cleaning the black profile cover</td>
<td>OFF</td>
<td>Alignment between transmitter and receiver OK, when the OSSD are enabled</td>
</tr>
<tr>
<td>Blanking</td>
<td>1 flash</td>
<td>Fixed blanking of the protection field(s)</td>
</tr>
<tr>
<td>2 flash</td>
<td>Floating blanking, max. 1 beam</td>
<td></td>
</tr>
<tr>
<td>3 flash</td>
<td>Floating blanking, 2 beams</td>
<td></td>
</tr>
<tr>
<td>4 flash</td>
<td>Floating (max. 1 beam) and fixed blanking of protection field(s)</td>
<td></td>
</tr>
<tr>
<td>5 flash</td>
<td>Floating (2 beams) and fixed blanking of protection field(s)</td>
<td></td>
</tr>
<tr>
<td>6 flash</td>
<td>Fixed blanking with movable edge region</td>
<td></td>
</tr>
<tr>
<td>Information</td>
<td>flashing</td>
<td>Beam coding A is active</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Transmitter LED</th>
<th>Status LED</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Transmitting</td>
<td>On</td>
<td>Standard operation, transmitter active</td>
</tr>
<tr>
<td>flashing</td>
<td>Configuration error</td>
<td></td>
</tr>
<tr>
<td>Information</td>
<td>flashing</td>
<td>Beam coding A is active</td>
</tr>
</tbody>
</table>
6.2 Fault diagnostic
The light curtain performs an internal self-test after the operating voltage is switched on and the protection field is enabled. When a fault is detected, an error number e.g. E1 is displayed at the receiver. Each fault display is followed by a one-second delay.

<table>
<thead>
<tr>
<th>Status display</th>
<th>Fault feature</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Wiring error operating mode not defined</td>
<td>Check all connections at the receiver, Jumper connection 1 or jumper connection 2 present?</td>
</tr>
<tr>
<td></td>
<td>Supply voltage</td>
<td>UB = 24V/DC+/− 10%, check voltage source and primary voltage, note: after the fault message E2 has been displayed three times, a reset is executed.</td>
</tr>
<tr>
<td></td>
<td>Error output (e), OSSD1 or OSSD2</td>
<td>Check the connections of both outputs, short-circuit of both OSSD, connection to level 0V or 24V, deactivate external (relay) cross-wire short monitoring</td>
</tr>
<tr>
<td></td>
<td>Contactor control (EDM)</td>
<td>EDM active: check connections of both NC contacts, EDM not active: check level at Pin 8, open input</td>
</tr>
<tr>
<td></td>
<td>Beam blanking</td>
<td>Check the blanking area(s) of fixed or floating objects with the selected parameter setting, fault elimination - repeat configuration in the parameter setting, possibly adjust P 1, P 2, P 3</td>
</tr>
<tr>
<td></td>
<td>Configuration error in parameter setting</td>
<td>Check parameter setting and save/adopt with &quot;S.&quot; or delete/reset with &quot;C.&quot;</td>
</tr>
<tr>
<td></td>
<td>System error</td>
<td>Restart the system, if E 7 display persists, exchange components</td>
</tr>
</tbody>
</table>

The error display is reset after elimination of the error cause and after the receiver has been switched back on. The error indication displays a 3-digit system error code for every 10th display.

7. Disassembly and disposal

7.1 Disassembly
The safety switchgear must be disassembled in a de-energised condition only.

7.2 Disposal
The safety switchgear must be disposed of in an appropriate manner in accordance with the national prescriptions and legislations.

8. Appendix

8.1 Contact
Consultancy / Sales:
K.A. Schmersal GmbH
Industrielle Sicherheitsschaltsysteme
Möddinghofe 30
D-42279 Wuppertal
Tel:+49 (0) 202 64 74 -0
Fax:+49 (0) 202 64 74- 100

You will also find detailed information regarding our product variety on our website: www.schmersal.com

Repair handling / shipping:
Safety Control GmbH
Am Industriepark 11
D-84453 Mühldorf/ Inn
Tel.: +49 (0) 8631-18796-0
Fax: +49 (0) 8631-18796-1
## Appendix

### 8.2 EC Declaration of conformity

**EC Declaration of conformity**

| Translation of the original declaration of conformity | Safety Control GmbH  
Am Industriepark 33  
84453 Mühldorf / Inn  
Germany |
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Name of the safety component / type:</td>
<td>SLC 440</td>
</tr>
<tr>
<td>Description of the safety component:</td>
<td>Safety light curtain</td>
</tr>
</tbody>
</table>
| Harmonised EC-Directives: | 2006/42/EC-EC-Machinery Directive  
2004/108/EC EMC-Directive |
CLC/TS 61496-2:2006  
EN ISO 13849-1:2008; Pl e  
EN 62061:2005; SIL 3 |
| Person authorised for the compilation of the technical documentation: | Ulrich Loss  
Möddinghofe 30  
42279 Wuppertal |
| Notified body for the prototype test: | TÜV Nord Cert GmbH  
Langemarckstr. 20  
45141 Essen  
ID n°: 0044 |
| EC-prototype test certificate: | n° 44205 11 39374 0000 |
| Place and date of issue: | Mühldorf, September 19, 2011 |

The currently valid declaration of conformity can be downloaded from the internet at www.schmersal.net.